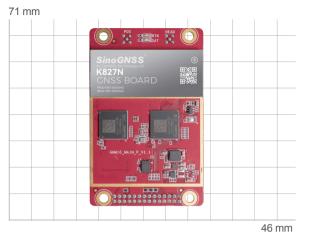
K827N GNSS Board



Size(L × W × H): 46 mm × 71 mm × 10 mm Weight: 15g

Features

Full-constellation multi-frequency

Support GPS, BDS-2, BDS-3, GLONASS, Galileo,

NavIC, QZSS and SBAS

Unique Dual-engine RTK technology

Support INS+GNSS navigation

Support L-Band* and S Band

Support CAN protocol*

50Hz data output*

Dual-engine RTK Technology

Embedded with advanced Dual-Engine RTK technology,observations from primary antenna and secondary antenna are transferred to two processors where RTK are computed independenty. The robustness of system is improved as redundant measurements from a secondary antenna can significanty improve the avaiability of the positioning result in complex environments.

Flexible Integration

K827N is easy for integration with its 1.8W lower power consumption and smallsize.With support of CAN protocol,K827N can meet demands in automobile electric field.

K827N GNSS Board

Advanced Anti-interference Technology

Based on our latest QUANTUM III SoC chip with outstanding self-adaptive Anti-interference Technology,K827N can suppress the wideband,narrowband and continuous-wave interference. It can provide users with high-quality observing data in the complex electromagnetic environment.

On Board IMU

K827N combines GNSS and IMU to deliver precise positioning in challenging environment, such as urban canyons, under trees or bridges. When losing GNSS signal, it can keep centimeter level positioning in 3s and meter-level in 10s.

Strong Compatibility

Designed with standard I/O and pin definition,the K827N is compatible with mainstream GNSS boards from physical to data format,ensuring a seamlessly replacement for customers who use boards on worldwide standard 20pins to 28pins.

Dual-antenna Input

With dual antenna design, K827N can deliver robust positioning and heading. It is capable of providing centimeter-accuracy positioning and high-precision heading both in static and dynamic scenes.

Full-constellation and Multi-frequency

K827N can track all the current and planned GNSS constellations, including GPS,BDS-2,BDS-3,GLONASS,Galileo, NavIC,QZSS and SBAS.Your GNSS solutions will never be outdated with K827N GNSS boards.



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K827N GNSS Board

K Series GNSS Module Ver.2024.05.06

Positioning	
GPS	L1C/A,L1C,L2P,L2C,L5
BDS-2	B1,B2I,B3I
BDS-3	B1I,B3I,B1C,B2a,B2b
GLONASS	G1,G2,G3*
Galileo	E1,E5b,E5a,E5AltBoC*,E6c
QZSS	L1C/A,L2C,L5,L1C*
SBAS	L1C/A
NavIC	L5, S Band
L-band*	

Heading (& Positioning 2)

L1C/A,L1C,L2P,L2C,L5
B1,B2I,B3I
B1I,B3I,B1C,B2a,B2b
G1,G2,G3*
E1,E5b,E5a,E5AltBoC*,E6c
L1C/A,L2C,L5,L1C*

Performance Specifications

Cold Start	<20s (Adding Acceleration Capture Module)
Hot Start (with RTC)	<10s (Typical)
Reacquisition	<1s
RTK Initialization time	<5s (baseline<10km)
Initialization Reliability	>99.9%
Velocity Accuracy	≤0.02m/s (PDOP≤4)
Time Accuracy	20ns
Overload	15g

Heading Specification

Azimuth Roll or Pitch 0.15°/R 0.25°/R

Positioning Specification

Single Baseline RTK	8 mm+1 ppm Horizontal 15mm+1 ppm Vertical
Post Processing	2.5 mm+1 ppm Horizontal 5mm+1 ppm Vertical
DGPS	<0.4m RMS
SBAS	1m 3D RMS
Standalone	1.5m 3D RMS

"*"upgradeable

1.R(meter)is the length of two GNSS antennas.

Data Format		
Correction data I/O	RTCM2X, 3X, CMR (GPS only), CMR+(GPS only)	
Position data output	-ASCII: NMEA-0183 GGA, GSA, GSV, RMC, HDT, VHD, ZDA, VTG, GST, GLL; PTNL, PJK; PTNL, AVR; PTNL, GGK -ComNav Binary -Position data output rate: 1 Hz, 2 Hz, 5 Hz, 10Hz,20Hz	
Antenna Interface		
Impedance Matching	50 Ω	
LNA Power External	+3.3V~+5.0V±5%VDC@0-100mA	
LNA Gain	20~35dB	
Physical		
Size	46mm×71mm×10mm	
Weight	15.0g	
Hardware interface	28pin	
Environmental		
Working temperature	-40 °C to + 85 °C	
Storage temperature	-55 °C to + 95 °C	
Electrical		
Input voltage	+3.3V~5.0V±5%DC @0~100mA	
Power consumption	1.8 W (Anti-interference off) Set anti-interference on consumes more about 0.2w	
Software		
ComNav Compass Receiver Utility software		
Compass Solution software		

Optional Accessories

AT-series GNSS antenna		
Evaluation Kit		
5m/10m RF Cables		

Communications	
LVTTL ports	x3
SPI	x2
Event Marker input	x2
Pulse Per Second(PPS)output	x1
Indicator pins show the working status	х3





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